

Contraction Wedge Duality and Double Forms

Evan Gawlik¹ Anil N. Hirani²

¹Santa Clara University

²University of Illinois at Urbana-Champaign

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Outline

- 1 Contraction, Lie derivative and PDEs
- 2 Contraction wedge duality and DEC
- 3 Double forms and Bianchi sums

1 Contraction, Lie derivative and PDEs

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Recall: Contraction and Lie derivative

Contraction

For $\alpha \in \Omega^k(M)$ and X a vector field, *contraction* of α is $i_X \alpha \in \Omega^{k-1}(M)$ defined as

$$i_X \alpha(\dots) = \alpha(X, \dots)$$

Lie derivative

The *Lie derivative* of α along X is

$$\mathcal{L}_X \alpha := \left. \frac{d}{dt} \right|_{t=0} \varphi_t^* \alpha$$

where φ is the flow of X on M .

Cartan Formula

$$\mathcal{L}_X \alpha = di_X \alpha + i_X d\alpha$$

Example PDE applications

- ▶ Mass continuity

$$\partial_t \rho + \operatorname{div}(\rho u) = 0 \quad \Longleftrightarrow \quad \partial_t(\rho \mu) + d(\rho i_u \mu) = 0$$

ρ = density and μ = volume form

- ▶ Advection

$$\partial_t \alpha + \mathcal{L}_u \alpha = 0$$

- ▶ Navier-Stokes $(u \cdot \nabla)u$ term is vector proxy for

$$\mathcal{L}_u u^b - \frac{1}{2} di_u u^b$$

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An old contraction formula

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Proof sketch (upto sign):

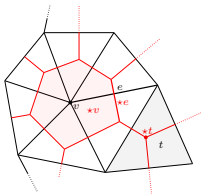
- ▶ Let $e_1, \dots, e_n$ be orthonormal frame around a point and $e^1, \dots, e^n$ coframe
[$e^i(e_j) = \delta_j^i$]
- ▶ Enough to show

$$i_{e_j} e^I = \pm * (*e^I \wedge e^j)$$

where $e^I = e^{i_1} \wedge \dots \wedge e^{i_k}$, $i_1 < \dots < i_k$

- ▶ RHS is $\pm * (e^{\bar{I}} \wedge e^j)$ where $\bar{I}$ is complement of I as set
- ▶ If $j \notin I$ then LHS=RHS=0
- ▶ If $j \in I$ then LHS is $\pm e^{I \setminus \{j\}}$ and RHS is $*(e^{\bar{I}} \wedge e^j) = \pm * e^{\bar{I} \cup j} = \pm e^{I \setminus \{j\}}$

DEC motivation for formula



- Hodge star as ratio of primal and dual

$$\langle \star \alpha, \star \sigma \rangle = \frac{|\star \sigma|}{|\sigma|} \langle \alpha, \sigma \rangle$$

- Wedge product as anti-symmetrized cup

$$\langle \alpha \wedge \beta, [v_0, \dots, v_{k+l}] \rangle = \frac{1}{(k+l+1)!} \sum_{\tau \in S_{k+l+1}} \text{sgn}(\tau) \langle \alpha \smile \beta, [v_{\tau(0)}, \dots, v_{\tau(k+l)}] \rangle$$

- $i_X \alpha = (-1)^{k(n-k)} \star (\star \alpha \wedge X^\flat)$ gives a way to discretize contraction
- Cartan formula $\mathcal{L}_X \alpha = d i_X \alpha + i_X d \alpha$ gives a way to discretize Lie derivative

Contraction formula in practice

► Geophysical fluid dynamics:

- C. Eldred and W. Bauer. “An interpretation of TRiSK-type schemes from a discrete exterior calculus perspective”, arXiv:2210.07476.
- W. Bauer. “A new hierarchically-structured n-dimensional covariant form of rotating equations of geophysical fluid dynamics”, Int. J. Geomath, 2016.

► Navier-Stokes:

- M. S. Mohamed, A. N. Hirani, and R. Samtaney. “Discrete exterior calculus discretization of incompressible Navier-Stokes equations over surface simplicial meshes”, J. Comp. Physics, 2016.
- P. Jagad, A. Abukhwejah, M. Mohamed, and R. Samtaney. “A primitive variable discrete exterior calculus discretization of incompressible Navier-Stokes equations over surface simplicial meshes”, Physics of Fluids, 2021.
- M. Wang, P. Jagad, A. N. Hirani, and R. Samtaney. “Discrete exterior calculus discretization of two-phase incompressible Navier-Stokes equations with a conservative phase field method”, J. Comp. Physics, 2023.

Contraction formula as L^2 -duality

L^2 -duality of contraction and wedge

For k -form α , $(k-1)$ -form β

$$(i_X \alpha, \beta)_{L^2} = (\alpha, X^\flat \wedge \beta)_{L^2}$$

Contraction formula as L^2 -duality

L^2 -duality of contraction and wedge

For k -form α , $(k-1)$ -form β

$$(X \lrcorner \alpha, \beta)_{L^2} = (\alpha, X^\flat \wedge \beta)_{L^2}$$

Contraction formula as L^2 -duality

L^2 -duality of contraction and wedge

For k -form α , $(k-1)$ -form β

$$(i_X \alpha, \beta)_{L^2} = (\alpha, X^\flat \wedge \beta)_{L^2}$$

μ volume form associated with the metric

$$\begin{aligned} \langle i_X \alpha, \beta \rangle \mu &= \langle \beta, i_X \alpha \rangle \mu = \beta \wedge * i_X \alpha \\ &= \beta \wedge (-1)^{k(n-k)} * (*\alpha \wedge X^\flat) \\ &= (-1)^{k(n-k) + (n-k+1)(k-1)} \beta \wedge (*\alpha \wedge X^\flat) \\ &= (-1)^{k(n-k) + (n-k+1)(k-1) + (n-k)} \beta \wedge (X^\flat \wedge *\alpha) \\ &= (-1)^{(k+1)} ((\beta \wedge X^\flat) \wedge *\alpha) \\ &= (-1)^{(k+1)(k-1)} ((X^\flat \wedge \beta) \wedge *\alpha) \\ &= \langle X^\flat \wedge \beta, \alpha \rangle \mu = \langle \alpha, X^\flat \wedge \beta \rangle \mu \end{aligned}$$

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Double forms

q -form valued p -form

$$\Omega^{p,q}(M) = \Omega^p(M; \Lambda^q T^*M) = \Gamma(\Lambda^p T^*M \otimes \Lambda^q T^*M)$$

- ▶ Introduced by de Rham and used in differential geometry, analysis, and numerical analysis.
- ▶ For $\varphi \in \Omega^{p,q}(M)$ and vector fields $X_1, \dots, X_p, Y_1, \dots, Y_q$

$$\varphi(X_1, \dots, X_p)(Y_1, \dots, Y_q) \in C^\infty(M)$$

- ▶ Decomposable double forms are like $\alpha \otimes \beta$ with $\alpha \in \Omega^p(M)$ and $\beta \in \Omega^q(M)$.

Grid of de Rham sequences for BGG

$$\begin{array}{ccccccccc}
 \Omega^{0,0} & \xrightarrow{d_{\nabla}^{00}} & \Omega^{1,0} & \xrightarrow{d_{\nabla}^{10}} & \Omega^{2,0} & \xrightarrow{d_{\nabla}^{20}} & \Omega^{3,0} & \xrightarrow{d_{\nabla}^{30}} & \Omega^{4,0} \rightarrow \dots \\
 & \nearrow s_{01} & & \nearrow s_{11} & & \nearrow s_{21} & & \nearrow s_{31} & \\
 \Omega^{0,1} & \xrightarrow{d_{\nabla}^{01}} & \Omega^{1,1} & \xrightarrow{d_{\nabla}^{11}} & \Omega^{2,1} & \xrightarrow{d_{\nabla}^{21}} & \Omega^{3,1} & \xrightarrow{d_{\nabla}^{31}} & \Omega^{4,1} \rightarrow \dots \\
 & \nearrow s_{02} & & \nearrow s_{12} & & \nearrow s_{22} & & \nearrow s_{32} & \\
 \Omega^{0,2} & \xrightarrow{d_{\nabla}^{02}} & \Omega^{1,2} & \xrightarrow{d_{\nabla}^{12}} & \Omega^{2,2} & \xrightarrow{d_{\nabla}^{22}} & \Omega^{3,2} & \xrightarrow{d_{\nabla}^{32}} & \Omega^{4,2} \rightarrow \dots \\
 & \nearrow s_{03} & & \nearrow s_{13} & & \nearrow s_{23} & & \nearrow s_{33} & \\
 \Omega^{0,3} & \xrightarrow{d_{\nabla}^{03}} & \Omega^{1,3} & \xrightarrow{d_{\nabla}^{13}} & \Omega^{2,3} & \xrightarrow{d_{\nabla}^{23}} & \Omega^{3,3} & \xrightarrow{d_{\nabla}^{33}} & \Omega^{4,3} \rightarrow \dots \\
 \vdots & & \vdots & & \vdots & & \vdots & & \vdots
 \end{array}$$

Bianchi sums s and s^*

$$s_{p,q} : \Omega^{p,q}(M) \rightarrow \Omega^{p+1,q-1}(M)$$

$$(s\varphi)(X_1, \dots, X_{p+1})(Y_1, \dots, Y_{q-1}) = \sum_{i=1}^{p+1} (-1)^{i-1} \varphi(X_1, \dots, \hat{X}_i, \dots, X_{p+1})(X_i, Y_1, \dots, Y_{q-1})$$

$$s_{p,q}^* : \Omega^{p,q}(M) \rightarrow \Omega^{p-1,q+1}(M)$$

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where X 's and Y 's are vector fields.

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where X 's and Y 's are vector fields. (Actually only needs vectors at a point.)

Contraction wedge duality and Bianchi sums (1)

Proposition 2.7 in Y. Berchenko-Kogan and E. S. Gawlik. “Finite element spaces of double forms”, arXiv:2505.17243:

Alternate characterization of s and s^*

$$s(\alpha \otimes \beta) = \sum_{i=1}^n (e^i \wedge \alpha) \otimes (e_i \lrcorner \beta)$$
$$s^*(\alpha \otimes \beta) = \sum_{i=1}^n (e_i \lrcorner \alpha) \otimes (e^i \wedge \beta)$$

Proposition 2.8 in arXiv:2505.17243:

Adjointness

s and s^* are adjoints of each other.

► Proof uses contraction wedge duality.

Contraction wedge duality and Bianchi sums (2)

- For $A \in \Omega_{\text{sym}}^{1,1}$ define $i_A : \Omega^{p,q}(M) \rightarrow \Omega^{p+1,q-1}(M)$

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- ▶ For $g = \sum_{i=1}^n e^i \otimes e^i$

$$i_g(\alpha \otimes \beta) = \pm \sum_{i=1}^n (e^i \wedge \alpha) \otimes *(e^i \wedge *\beta)$$

Contraction wedge duality and Bianchi sums (2)

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Lemma 3.6 in R. Kupferman and R. Leder. “Elliptic pre-complexes, Hodge-like decompositions and overdetermined boundary-value problems”, Forum of Mathematics, Sigma 13, 2025:

s operator and metric

$$s = i_g$$

- ▶ Proof uses contraction wedge duality.

Summary and conclusion

- ▶ Contraction is a useful operator in numerical methods for PDEs
- ▶ Contraction and wedge are L^2 duals
- ▶ This duality shows up in various interpretations of Bianchi sums
- ▶ This viewpoint may be useful to construct DEC-like Bianchi sum operators